Instrumental Sensing of Stationary Source Emissions

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Remote sensing methods offer a number of advantages over current measurement methods in the area of enforcement and surveillance of emissions from stationary sources. Several techniques have been developed that can measure the gas concentration, effluent opacity, and particulate opacity. The opacity measurement is capable of what a gas emission rate may be determined. To evaluate the accuracy, utility, and costs of development of some of these techniques, a series of measurements were conducted at coal-burning power plants to which the results of the remote measurements were compared with the results of in-stack measurements made using EPA reference methods. The techniques studied and the properties measured were (1) infrared gas-filter correlation radiometry (GFC), (2) Fourier-transform spectroscopy (FTS), (3) ultraviolet differential absorption spectroscopy (UVDS), (4) infrared and ultraviolet differential absorption spectroscopy (DIAL), (5) infrared laser heterodyne radiometry (HRS), and (6) visible light laser opacity (LO). The techniques used, procedures, the measurement results, and recommendations for overcoming and using remote sensing techniques for measuring emissions from pollutant sources are discussed.

Air pollution Remote sensing Sulfur dioxide Plumes Optical measuring instruments Correlation		13B 14B 07B 04B
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Instrumental sensing of stationary source emissions

Ground-based remote sensing techniques are under development and testing

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For the use of remote sensing to be cost-effective for stationary source emissions measurements, a number of criteria must be satisfied. The system must be capable of measuring the pollutant species of interest with sufficient accuracy and precision. It must be capable of operating unattended for long periods of time. It must be relatively inexpensive to purchase and operate. It must be capable of measuring a sufficient number of sources to justify the cost of the system. Finally, it must be capable of measuring the pollutant species of interest under the conditions of interest.

Instrumental remote sensing methods have been used for a number of stationary source measurements. Various techniques have been used, but a common feature of most of these techniques is the use of a radiation source and a detector to identify and measure the concentration of various pollutants in the atmosphere. In some cases the development of a new instrument or technique for remote measurement of the concentration of pollutants emitted by stationary sources has been inadequately quick. Also, a number of these techniques have proven to be inherently difficult and costly to implement and use. Nevertheless, the use of remote sensors for continuous monitoring could be practical. The particular advantage of a remote sensor over a contact sensor in these applications is its ability to monitor a number of different sources sequentially in a relatively short time. In enforcement activities, where a single remote sensor could be used to monitor several sources per day, it is estimated that operational costs would be one tenth the cost of contact sensors, although the initial cost of the remote sensor could probably be significantly more than that of the contact sensor. Other advantages of remote sensors for enforcement purposes are that they can monitor emissions of an uncooperative source without having access to the source property, and most of the sensors can operate at night as well as during the day.

A variety of programs have been conducted within EPA over the past several years to evaluate the capability of various ground-based remote sensing techniques for measuring the SO_2 concentration, velocity, and opacity of effluents from coal-burning power plants.

Measurement programs

Several techniques have been developed that can measure the concentration and velocity of gaseous species and particulate opacity. The velocity measurement is needed so that a mass emission rate may be determined. In order to evaluate the accuracy, utility, and costs of development of some of these techniques, a series of measurements have been conducted at coal-burning power plants, and the results of the remote measurements were compared with the results of known measurements made using the EPA reference methods. The techniques tested in these programs are:

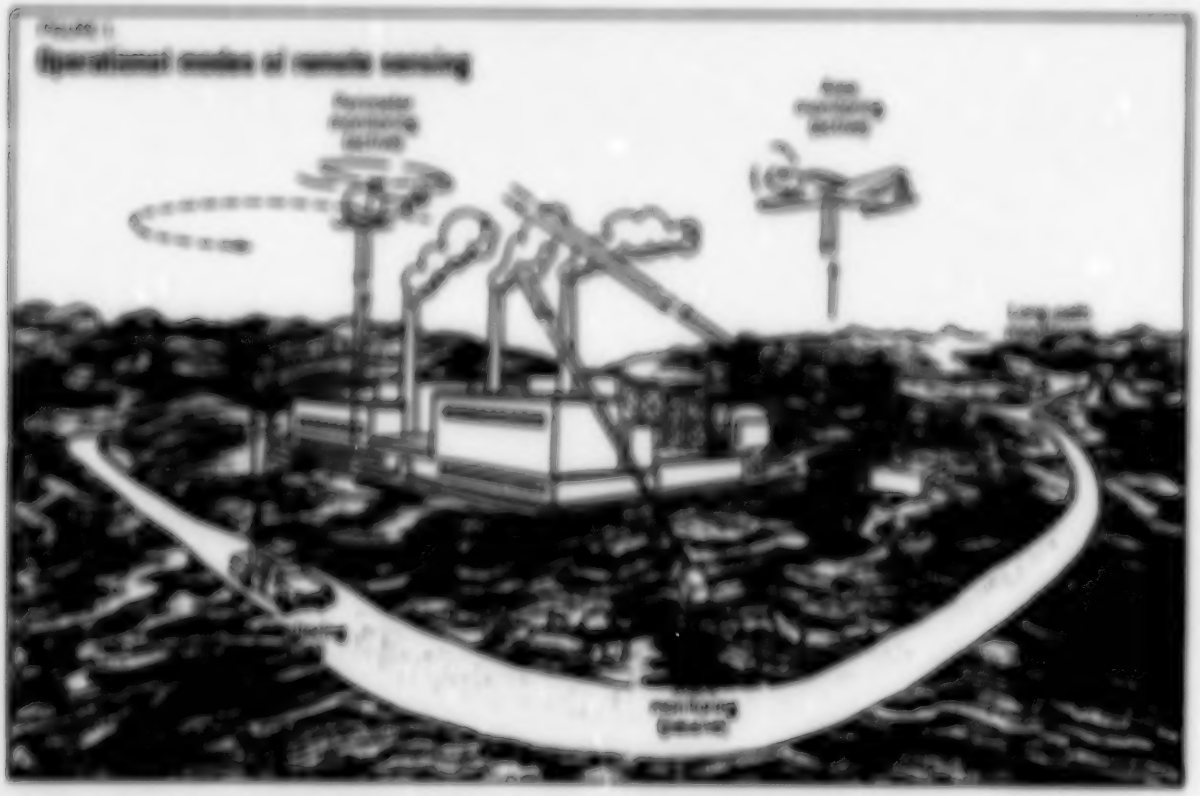
- Infrared gas filter correlation radiometry (IRFCR), for SO_2 concentration
- Fourier transform infrared spectroscopy (FTIR), for SO_2 concentration
- Ultraviolet differential correlation spectroscopy (UVDCS), for SO_2 concentration
- Ultraviolet and ultraviolet extinction (UVT) and (UVTX), for opacity and SO_2 concentration
- Infrared laser Doppler velocimetry (LDV), for plume velocity
- Lidar, laser radar (lidar), for plume opacity

The emphasis in the work described in measurements of gaseous species concentrations has been on techniques not requiring plume mixture or transit velocity. For remote velocity and opacity measurements, techniques using lasers are well developed.

IRFCR technique is able to measure SO_2 concentrations in the 500 ppm range with an accuracy of about 10% as compared with Reference Method 6 for a plume 4 m thick at a temperature of about 300 °C. The present instrument does become inoperative if any of the parameters—pathlength, concentration, or temperature—drop much below the above values. The IRFCR is an ideal remote sensor in that one person is able to operate the instrument and reduce the data, and the instrument is cost to not exceed about $20 000. Furthermore, the overall performance of the instrument can probably be significantly improved through the use of cooled detectors, more efficient optics, and better calibration procedures. The technique is readily adaptable to other gases such as CO, HF, and HCl.

FTIR is probably capable of yielding greater accuracy than the IRFCR if a reliable plume temperature can be determined. However, its present cost, complexity of data reduction and complexity of operation are much greater for the FTIR than for the IRFCR. Since most pollutant monitoring is done on a single pollutant basis, the IRFCR must rate well ahead of the FTIR in overall practicality for enforcement needs. In cases arise where multipollutant monitoring becomes important, the FTIR could become more practical.

For general research studies to characterize gaseous pollutants emitted by various types of sources and to determine optimum spectral regions for the operation of specialized instruments (for example, the IRFCR), an FTIR system will remain the most suitable spectroscopic method. This type of research activity is being conducted at EPA; the grating spectrometer used in the past has been replaced by an FTIR coupled to telescopic optics. The system is mounted



Volume 11, Number 10, October 1977 883

TABLE I

Summary of selected remote sensing techniques

Technique	Species	Source	Path	Remarks
Optical techniques				
Differential absorption	SO_2, NO_x, O_3	Mercury vapor	Stack, duct, or perimeter	Commercially available; day only operation; multispecies and experimental; low sensitivity; 1 dimensional
LIDAR	SO_2	Ruby laser	Stack or duct	Experimental; day or night for plume; night only during development
DIAL	O_3	Tunable dye laser	Stack or perimeter	Experimental; day or night for plume; high potential for mass monitor
Long-path absorption	SO_2, NO_x, O_3	Mercury vapor	Duct or perimeter	Lab tested only; requires a 10 m path; systems are bulky; mobile system
Raman	SO_2, NO_x	Mercury vapor	Stack	Day; lab tests; low sensitivity
Fabry-Perot Etalon	SO_2, NO_x	Mercury vapor	Stack	Lab tested only; has increased sensitivity over grid method
Fluorescence	SO_2, NO_x	Mercury vapor	Stack	Lacks sensitivity and specificity
Passive techniques				
Spectral filter correlation	SO_2, NO_x	SO_2, CO_2	Stack or perimeter	Commercially available; day, limited operation only
Gas filter correlation	O_3	SO_2	Stack or perimeter	Stack instrument field tested; duct instrument under development; day or night use; Potential for many gases
Tomography	SO_2	Opacity	Stack	Needs further development
Infrared	CO, O_3	SO_2, and velocity	Stack	Needs continued development and evaluation
Optical-acoustic correlation	O_3	Mercury vapor	Stack or duct	Lab tested only; field testing planned
Spectrometer	O_3	Mercury vapor	Stack	Requires high resolution grating or interferometer instrument for sensitivity and temperature data

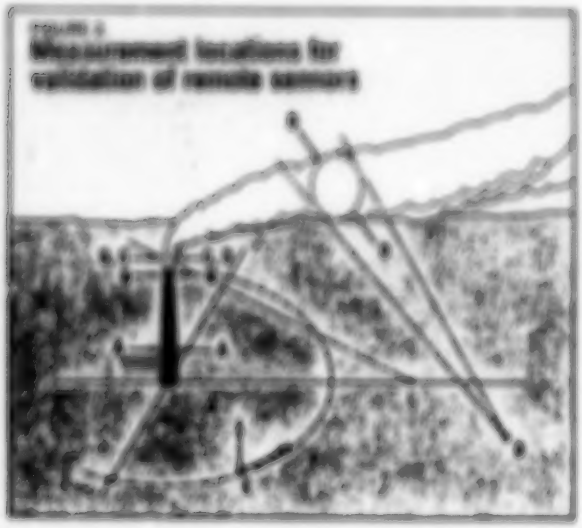
the pollutant optical depth (product of concentration and path length) in a vertical column surrounding the stack. These data, coupled with the local wind velocity, allow calculation of a mass emission rate. This type of perimeter measurement is especially applicable to extended area sources, but the validation is most accurately done on a single isolated stack.

Most of the measurements described in the article were conducted at the Riverbend Steam Plant of Duke Power Company near Charlotte, N.C. At this four-unit, 800-MW, coal-burning power plant, the EPA Emissions Measurement and Characterization Division, with the cooperation of Duke Power Company, conducts many of its instrumentation test and evaluation programs. One stack at this plant is fitted with a number of ports to allow attachment of various cross-stack and extractive monitoring systems. The semipermanent equipment includes a Lear-Siegler Model 500 transmissometer to measure opacity and a Du Pont Model 460-1 continuous extractive analyzer for SO_2 and NO_x.

The remote measurement site at Duke Power is about 600 m plant range from the top of the instrument stack; the line-of-sight is about 9° above the horizontal. Most of the remote measurements are made from this site, but other sites are also used. The ports on the instrument stack are between 1–3 m above the plant roof level. There is a ladder to the top of the stack to permit "B" type measurements. A small building has been assembled on the plant roof near the instrumented stack to house instrument recorders and to serve as a site laboratory. When plant operating conditions permit, the generating load can be varied to change the effluent exit velocity and selected precipitator sections can be shut off to increase plume opacity. In this way the effect of these known changes on the operation of the remote instruments is determined.

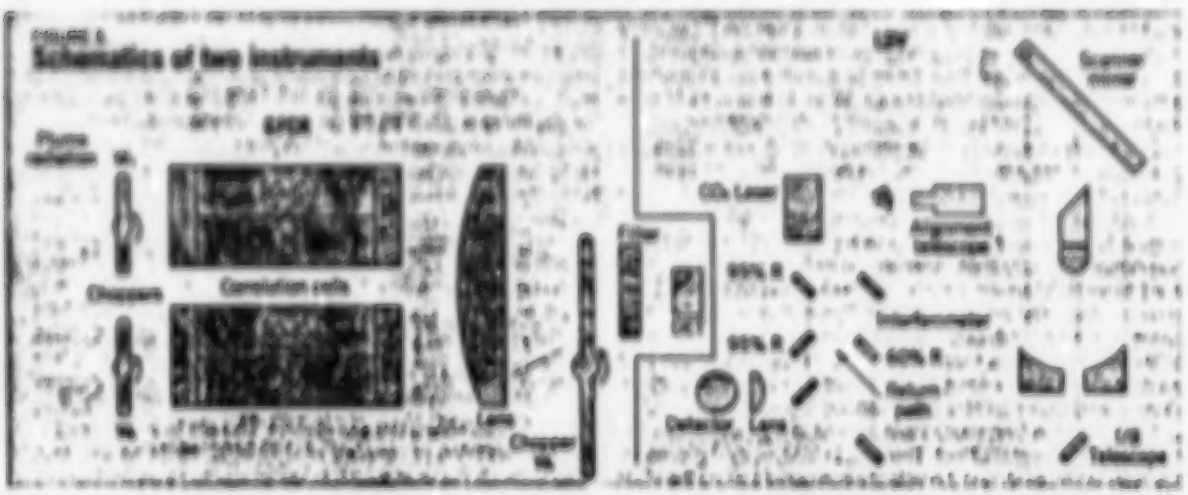
FIGURE 2

Measurement locations for validation of remote sensors



Measurements

The **EPCR** instrument was developed for EPA by Science Applications, Inc. The instrument's operating principles are indicated in the simplified schematic (Figure 3). Plume radiation traverses the two pairs of optical channels and is focused onto an infrared detector after being spectrally filtered and optically chopped at a carrier frequency of 800 hz (ω_0). The filter is centered at 2500 cm^{-1} and has a bandwidth of about 25 cm^{-1}. This particular configuration is optimized for SO_2 concentration measurements.


Plume radiation
Chopper
Correlation cells
Lens
Chopper
CO2 Laser
Beam splitter
Interferometer
Detector
Lens
Beam path
Scanner mirror
Aligment telescope
UV Telescope

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The stability measurement is most effectively made in the "operating" perimeter mode. In this mode, the SO_2 optical depth is measured in a vertical column surrounding the source in question. By also measuring the wind shear velocity, the SO_2 mass emission rate from the source may be calculated.

An evaluation of this type of measurement is now underway. Here, there is only a single stack serving as the source. This situation does not exist at the Duke Power Plant site, and a site was selected in the Southwest where a coal-burning plant was operating with a single stack. From measurements taken there, it was found that the LIDAR and in-stack mass emission rate measurements agreed to within 6.0%. The wind velocity measurements were considered to be a major source of error in these measurements. (Wind velocity was determined by tracking a pilot balloon with a theodolite.)

During August, 1974, a UVTV system developed by Dr. Reginald Eaton of NASA/Langley Research Center and an IRTV system developed by Mr. Edward Cross of Aerospace Corporation were both operated at the Duke Power Plant site. The UVTV produces a visible picture showing the attenuation of scattered solar UV energy by plume constituents; the plume appears darker than the bright sky background. The IRTV produces a visible picture of the infrared radiation from warm plume constituents; the plume appears brighter than the cool sky background.

The UVTV was shown to be able to measure SO_2 concentrations with an accuracy of 5.25% if the plume is relatively clean (opacity <20%). The data are obtained by filtering the camera first at 0.34 μm, where particulate opacity is measured, and then at 0.31 μm, where particulate opacity plus SO_2 opacity is measured. From these two measurements, the SO_2 attenuation can be determined and the concentrations calculated. Calibration is obtained by sighting the TV camera through cells that contain known amounts of SO_2. The IRTV is not able to measure SO_2 concentration because of a lack of spectral resolution and knowledge of the plume temperature.

It was anticipated that both systems would be able to measure the plume velocity, with the IR system having the advantage of being able to operate at night. The velocity was calculated by measuring the time required for gradients in the plume to travel a known distance, by using successive frames from the video-taped TV picture. The velocity determined in this manner was about a factor of two less than that determined from in-stack measurements. The assumed explanation for this is that the observed gradients are caused by the mixing of ambient air with the edges of the plume. Such a situation would be expected to produce a velocity somewhere between that of an ambient air and the true plume velocity. It was observed that the TV velocity did track the in-stack velocity in a regular manner during periods of velocity change, and thus it may be possible to demonstrate a consistent empirical relationship. Work in this area is continuing.

Since emission standards for stationary sources are generally based on a mass-emission rate, it is necessary to measure effluent velocity as well as concentration by remote methods to take full advantage of remote-sensing techniques. The LDV (Figure 3) technique has been in use for about 10 years to make non-contact velocity measurements in experiments concerning wind tunnels, clear-air turbulence, wake vortices and atmospheric winds. The principle of operation is simple. A CO_2 laser beam is propagated through the atmosphere and brought to focus at the desired range. Aerosols in the atmosphere scatter a fraction of the laser energy back toward a receiving telescope. Since the aerosol particles are in motion, backscattered energy will be shifted in frequency from the outgoing laser beam because of the Doppler effect. The shift in frequency depends on the laser wavelength and the velocity component along the laser beam. The backscattered energy as a function of the outgoing laser beam can be used to determine the velocity of the plume; a detailed description of this technique is given by Lawrence (1972).

In order to determine the feasibility of remotely measuring mass emission rates by LDV, a program was undertaken using an existing LDV system at the Duke Power Plant site. Measurements were conducted in August 1973 and January 1974, and the results have been described in detail by Miller and Conrad/Hilton (1975) (see Additional reading). Although the primary aim of the program was to demonstrate the feasibility of the remote velocity measurements, a secondary aim was to determine what, if any, relationship exists between the intensity of the backscattered signal and the attenuation coefficient of the plume (as determined from the opacity of the plume). It was shown that a reasonably linear relationship exists between plume attenuation coefficient and mass density for a given type of particulate source. Thus, the LDV measurement, utilizing a single instrument, has the potential to give a mass-emission rate for particulates.

Analysis of the velocity measurements found the LDV values within 10% of the in-stack values obtained by using EPA reference Method 2. Since reference Method 2 is considered accurate to ±5.0%, the agreement is about as good as might be expected. Although only two sets of data relating backscatter signal strength to plume attenuation coefficient were obtained, there is certainly good indication that a linear relationship exists. This relationship, if verified by additional measurements on a variety of sources, would allow a single LDV instrument to be used to measure a particle mass-emission rate when calibrated for a particular type of source.

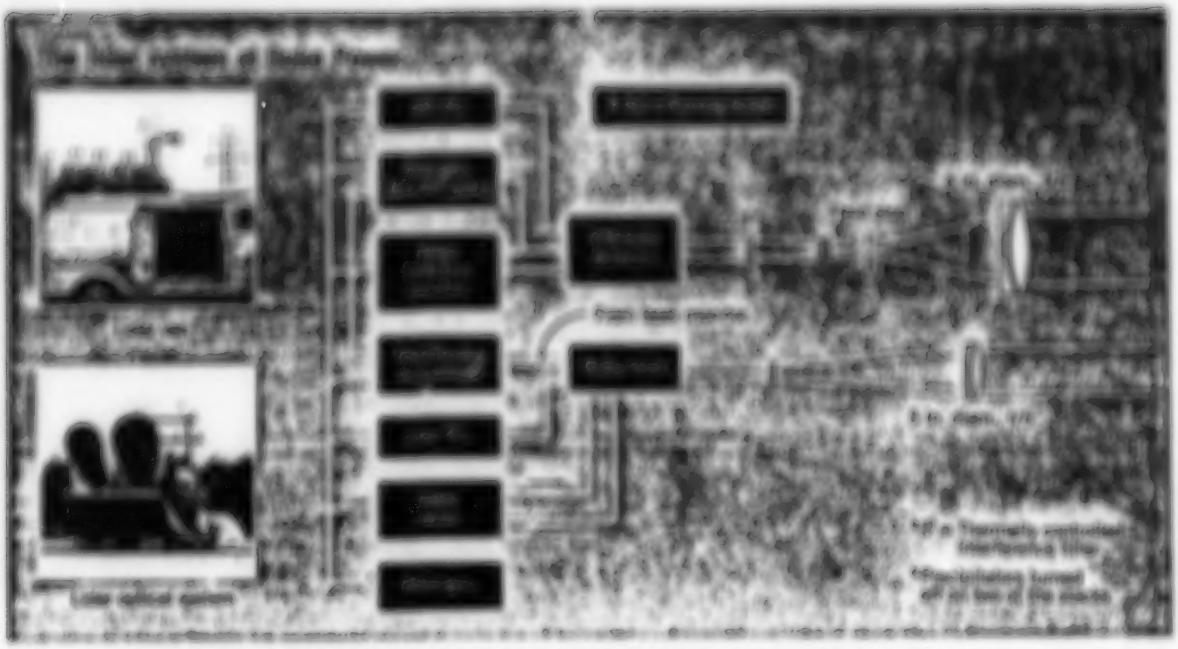
The lidar technique for remote measurement of plume opacity was first demonstrated by Evans (1967) (see Additional reading) who used lidar equipment designed for atmospheric studies. He showed that the opacity and transmittance of a plume could be determined by aiming the laser beam through the plume and comparing the relative backscatter intensity of the beam by the atmosphere in front of and behind the plume. In 1972, a van-mounted lidar designed for plume opacity measurements was developed for EPA by General Electric Company. This system is shown in operating configuration at the Duke Power Plant site in Figure 5. The operating characteristics of the system are given in Table 2.

The accuracy of the lidar was determined by using neutral density screen targets of known opacity. The opacity of 1-m diameter screens was determined by laboratory transmis-

TABLE 2

Mobile lidar systems characteristics

Component	Characteristic
Transmitter	
Laser	Rotating prism, Q-switched ruby
Wavelength	694.3 nm
Pulse width (FWHM)	<30 nanoseconds
Maximum output	1.0 joule
Repetition rate	3 pulses per minute
Cooling	Deionized water
Objective lens	12.7 cm, f/8
Beam divergence	~0.5 milradian full angle
Receiver	
Objective lens	15.25 cm, f/8
Field-of-view	4 milradian full angle
Bandpass (FWHM)	1.2 nm
Photomultiplier	IT&T F4084 (modified S-20)
Off-gating	≥60 dB
Response	~100 nanoseconds



corrections, which were in turn calibrated by using Kodak Wratten neutral density filters. The lidar opacity measurements of the calibrated targets were made at a distance of 200 m. The results indicated that the lidar is accurate to within 3% opacity for opacities less than 10%. At higher opacities the results showed maximum error of about −15% opacity for a targeted opacity of 100%. This decline in accuracy for opacities is of little concern since no opacity standards for emission sources are above 60% opacity.

A series of measurements were made at the Duke Power Plant site over several years at a range of 400 m to compare the lidar results with those of the instack transmissometer. The comparison showed a high degree of correlation (coefficient 0.993) between the remote lidar measurement and the instack measurement of opacity. However, the remote measurements were higher than the instack measurement by about 3% at the 5% instack opacity level and by about 8% at the 30% opacity level. Interestingly, the correlation would have been almost exact if no adjustment had been made for the stack diameter change at the top of the stack. This discrepancy demonstrates the need for making stack-exit measurements by using instack instrumentation at the stack exist as previously discussed.

Planned activities

The type of measurement that can be made with the MFCS (the "uplooking" perimeter measurement to yield mass-emission rates) has excellent potential for monitoring emissions from extended area sources, where no single stack is generally involved. For this reason the measurement concept is being extended to the infrared spectrum with the development of an "uplooking" GFCR instrument for SO_2 in a plume against the cold sky background. This type of instrument, first described in 1975, has the advantage (over the MFCS instrument) of being able to operate at night and of being applicable to a greater number of pollutants. A comparison of both the "uplooking" GFCR and the MFCS against the Reference Methods at an isolated stack was conducted during the summer of 1976. An LDV system, piballs, and a tethered balloon were used to measure the local wind velocity. The analyses of these data has not yet been completed.

Evaluations of the lidar system are still under way; comparisons are being made with both trained observer and instack transmissometer measurements. Work is being conducted by GRI International to develop a small portable lidar for remote plume opacity measurements that would cost approximately $200 000.

The continued cooperation of Duke Power Co. is gratefully acknowledged. Dr. H. M. Barnes, Mr. E. Foster, Mr. R. Rollins, and Mr. N. White, all of EPA, contributed significantly to various phases of the evaluation programs. Appreciation is also expressed to the contractors participating in the development and evaluations of the remote sensing instruments, and to NASA for assistance in funding and technical areas in the LDV programs.

Additional reading

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